

# Junjie Shen

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## Education

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| 2016–present | <b>Ph.D. in Computer Science, University of California, Irvine, CA</b><br><i>Advisor: Prof. Qi Alfred Chen</i><br><i>Research Interests:</i> Cyber-Physical Systems Security, Vulnerability Discovery, Adversarial Machine Learning.<br><i>GPA: 4.0/4.0</i> |
| 2014–2015    | <b>M.S. in Computer Engineering, North Carolina State University, Raleigh, NC</b><br><i>Advisor: Prof. Huiyang Zhou</i><br><i>GPA: 4.0/4.0</i>  |
| 2009–2013    | <b>B.E. in Communication Engineering, Hangzhou Dianzi University, Hangzhou, China</b><br><i>GPA: 3.3/4.0</i>  |

## Work Experience

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| Summer 2017 | <b>CPU Performance Modeling Intern at Qualcomm, Raleigh, NC.</b><br><i>Mentors: Dr. Arthur Perais and Dr. Luke Yen</i><br>Developed a tool to extract and break down instruction critical path in microarchitectural simulator. Helped identify several memory accessing and control flow bottlenecks in Qualcomm's ARM-based server CPU microarchitecture design.<br><b>Received a rating of superb in the intern performance review.</b> |
| Summer 2015 | <b>Research Intern at AMD Research, Beijing, China.</b><br><i>Mentor: Dr. Guoqing Chen</i><br>Characterized Convolutional Neural Network workloads on AMD GPUs. Exhaustively searched the GPU design space by adjusting computing units, GPU frequency, memory bandwidth, and cache size.  |
| Summer 2012 | <b>Software Engineering Intern at Uniview Technologies, Zhejiang, China</b><br>Developed Linux device driver for video encoders and decoders.  |

## Selected Projects

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| 2018–present | <b>Security analysis of Multi-Sensor Fusion (MSF) based Localization in Autonomous Vehicles</b><br>Performed the first security analysis on the state-of-the-art MSF-based localization algorithm in Autonomous Vehicle. Discovered a security vulnerability in the MSF design, and proposed an attack, which can successfully deviation the vehicle by 2 meters in 10 seconds using GPS spoofing.<br><i>Skills Involved: Binary Analysis, Cause Analysis, Optimization</i> |
| 2018–present | <b>Vulnerability Discovery in Open-source Autonomous Vehicle Systems</b><br>Wrote fuzzing tests for open-source Autonomous Vehicle systems such as Baidu Apollo and Autoware to find software vulnerabilities. Identify the limitations of the state-of-the-art fuzzers.<br><i>Skills Involved: Dynamic Analysis, Cause Analysis</i>  |
| 2017         | <b>Compiler assisted simultaneous fault and side-channel attack mitigation</b><br>Proposed a compiler-based mitigation technique to automatically strengthen vulnerable program against fault and side-channel attacks. Results showed that it can fully mitigates power side-channel attacks, and achieves 99.47% fault coverage on average.<br><i>Skills Involved: Intel Pin, LLVM, Correlation Power Analysis</i>  |

## Conference and Journal Publications

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| 2019 | Yunhan Jia, Yantao Lu, Junjie Shen, Qi Alfred Chen, Zhenyu Zhong, and Tao Wei. Fooling Detection Alone is Not Enough: First Adversarial Attack against Multiple Object Tracking. <i>arXiv preprint arXiv:1905.11026</i> , 2019  |
| 2019 | Vikram Narayanan, Abhiram Balasubramanian, Charlie Jacobsen, Sarah Spall, Scott Bauer, Michael Quigley, Aftab Hussain, Abdullah Younis, Junjie Shen, Moinak Bhattacharyya, and Anton Burtsev. LXDs: Towards Isolation of Kernel Subsystems. In <i>2019 USENIX Annual Technical Conference (USENIX ATC '19)</i> , 2019 |
| 2019 | Gongjin Sun, Junjie Shen, and Alex Veidenbaum. Combining Prefetch Control and Cache Partitioning to Improve Multicore Performance. In <i>IPDPS '19</i> . IEEE, 2019   |
| 2018 | Yonghua Mao, Junjie Shen, and Xiaolin Gui. A Study on Deep Belief Net for Branch Prediction. <i>IEEE Access</i> , 2018  |
| 2017 | Zhi Chen, Junjie Shen, Alex Nicolau, Alex Veidenbaum, Nahid Farhady Ghalaty, and Rosario Cammarota. CAMFAS: A compiler approach to mitigate fault attacks via enhanced SIMDization. In <i>FDTC '17</i> . IEEE, 2017   |

## Workshops and Posters

- 2019 | Junjie Shen, Jun Yeon Won, Shinan Liu, Qi Alfred Chen, and Alexander Veidenbaum. Poster: Security Analysis of Multi-Sensor Fusion based Localization in Autonomous Vehicles. In *NDSS Poster Session*, 2019. **Distinguished Poster Presentation Award**
- 2019 | Yunhan Jia, Yantao Lu, Junjie Shen, Qi Alfred Chen, Zhenyu Zhong, and Tao Wei. Fooling Detection Alone is Not Enough: First Adversarial Attack against Multiple Object Tracking. In *CVPR Adversarial Machine Learning in Real-World Computer Vision Systems Workshop*, 2019. **Selected as contributed talk**

## Talk

- Sept 25, 2017 | **CAMFAS: A compiler approach to mitigate fault attacks via enhanced SIMDization**  
In Fault Diagnosis and Tolerance in Cryptography workshop, Taipei, Taiwan

## Skills

- Programming Languages | C/C++, Python, Shell Script, Verilog HDL, Chisel
- Tools | LibFuzzer, Intel Pin, IDA Pro, GDB, Gem5
- Platforms | LLVM, Baidu Apollo Autonomous Driving Platform, Autoware, LGSVL Simulator, Openpilot, Linux Kernel